

Inefficient Automation

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Motivation

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- ▶ Two **literatures** can justify taxing automation.

Tax automation

Guerreiro et al 2017; Costinot-Werning 2018

- (i) Govt. has preference for redistribution
- (ii) Automation/reallocation are efficient

Tax capital (long-run)

Aiyagari 1995; Conesa et al. 2002

- (i) Improve efficiency in economies with IM
- (ii) Worker displacement/reallocation absent

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- ▶ Two **literatures** can justify taxing automation. **Reallocation** is **frictionless** or **absent**

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Take worker displacement seriously. **How should we respond to automation?**

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1. Recognize that displaced workers face two important **frictions**:
 - (i) **Slow reallocation**: workers face mobility barriers and may go through unempl./retraining
Davis-Haltiwanger, 1999; Jacobson et al, 2005; Lee-Wolpin, 2006; Alvarez-Shimer, 2011
 - (ii) **Imperfect credit markets**: workers have limited ability to borrow against future incomes
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4. **Quantitative**: gross flows + idiosync. risk \rightarrow **welfare gains** from slowing down autom.

Environment

Efficient Allocation


Decentralized Equilibrium

Failure of First Welfare Theorem

Optimal Policy

Quantitative Analysis

Continuous time $t \geq 0$



Continuous time $t \geq 0$

Occupations

Workers

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$h = A$ (share ϕ , degree $\alpha \geq 0$) or $h = N$

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Workers

Final Good Producer

$$G^*(\mu^A, \mu^N; \alpha) \equiv G(\{F^h(\mu^h)\})$$

(gross complements)

▶ Example

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$G^*(\mu^A, \mu^N; \alpha)$ concave in α (costly)

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$\mathbf{x} = \{s, h, \xi\}$ (age, occupation, prod.)

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$\mathbf{x} = \{s, h, \xi\}$ (age, occupation, prod.)

$$(\mu_t^A, \mu_t^N) \begin{cases} = 1 & \text{in } t = 0 \\ \text{Reallocation} & \text{afterwards} \end{cases}$$

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Resource constraint

$$\int c_t(\mathbf{x}) d\Lambda = G^*(\mu^A, \mu^N; \alpha)$$

$$\phi^h \mu_t^h = \int \mathbf{1}_{\{h(\mathbf{x})=h\}} \xi d\pi_t$$

Reallocation frictions

- ▶ Reallocation of existing workers is **costly** (Kambourov-Manovskii, Violante, Costinot-Werning)
 1. **Permanent cost**: productivity loss θ due to skill-specificity

$$\xi_t = \begin{cases} \lim_{\tau \uparrow t} \xi_\tau & \text{if } h'_t(\mathbf{x}) = h \\ (1 - \theta) \times \lim_{\tau \uparrow t} \xi_\tau & \text{otherwise} \end{cases}$$

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 2. **Random opportunities**: Workers can move across occupations with intensity λ
 3. **Unemployment/retraining spells**: Enter when moving, and exit at rate κ

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 2. **Random opportunities**: Workers can move across occupations with intensity λ
 3. **Unemployment/retraining spells**: Enter when moving, and exit at rate κ
- ▶ Arrival of new workers is **slow** (Rebelo et al., Adão et al.). Rate χ . Choose any occupation.

Environment

Efficient Allocation

Decentralized Equilibrium

Failure of First Welfare Theorem

Optimal Policy

Quantitative Analysis

First Best Problem

Ex post problem

Ex ante problem

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- ▶ Reallocate labor and distribute output
- ▶ Close **MPLs** gap. Stop reallocation at T_0^{FB}
(No OLG case)

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$$\int_{T_0^{\text{FB}}}^{+\infty} e^{-\rho t} u'(c_t^N) \Delta_t dt = 0$$

where

$$\Delta_t \equiv \underbrace{(1 - \theta) \left(1 - e^{-\kappa(t - T_0^{\text{FB}})} \right)}_{\text{Cost} = \text{Skill loss} + \text{unemp}} \overbrace{\mathcal{Y}_t^N - \mathcal{Y}_t^A}^{\text{MPL gap}}$$

is the IRF of Y to reallocation

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First Best Problem

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- ▶ Reduce C today, expand Y tomorrow

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where

$$\Delta_t^* \equiv \frac{\partial}{\partial \alpha} G^* (\mu_t^A, \mu_t^N; \alpha^{\text{FB}})$$

is the IRF of Y to automation (net of cost)

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Decentralized Choices

Firms

Workers

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Choose automation α + labor demand μ_t

$$\max_{\{\alpha, \mu_t\}} \int_0^{+\infty} Q_t \Pi_t(\mu_t; \alpha) dt$$

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Assets: riskless bonds

Workers not insured against automation risk

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Borrowing friction

$$a_t(\mathbf{x}) \geq \underline{a} \text{ for some } \underline{a} \leq 0$$

Firms

Choose automation α + labor demand μ_t

$$\max_{\{\alpha, \mu_t\}} \int_0^{+\infty} Q_t \Pi_t(\mu_t; \alpha) dt$$

No arbitrage $\rightarrow Q_t = \exp\left(-\int_0^t r_s ds\right)$

Equity priced by unconstrained workers

Workers

Choose cons. c_t and labor supply μ_t

Assets: riskless bonds

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Environment

Efficient Allocation

Decentralized Equilibrium

Failure of First Welfare Theorem

Optimal Policy

Quantitative Analysis

Failure of the First Welfare Theorem

Proposition. (Failure of FWT)

1. The laissez-faire equilibrium is inefficient if and only if **reallocation frictions** (λ, κ) and **borrowing frictions** (\underline{a}) are such that $a^*(\lambda, \kappa) < \underline{a} \leq 0$ for threshold $a^*(\cdot)$.

Failure of the First Welfare Theorem

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2. The threshold $a^*(\lambda, \kappa) < 0$ if and only if reallocation is slow ($1/\lambda$ or $1/\kappa > 0$).

Failure of the First Welfare Theorem

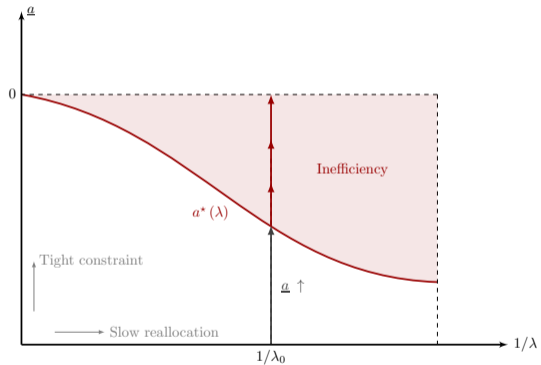
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► **Interaction** between reallocation and borrowing frictions \rightarrow inefficient automation

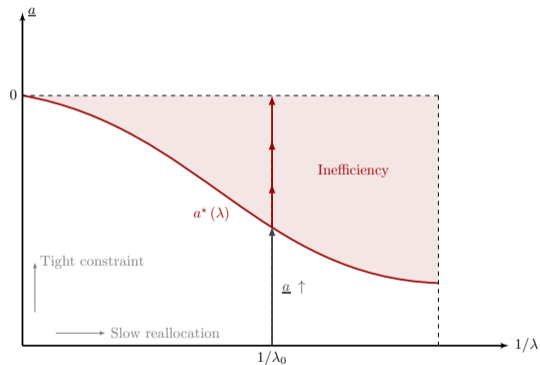
Failure of the First Welfare Theorem

Distortions at the laissez-faire



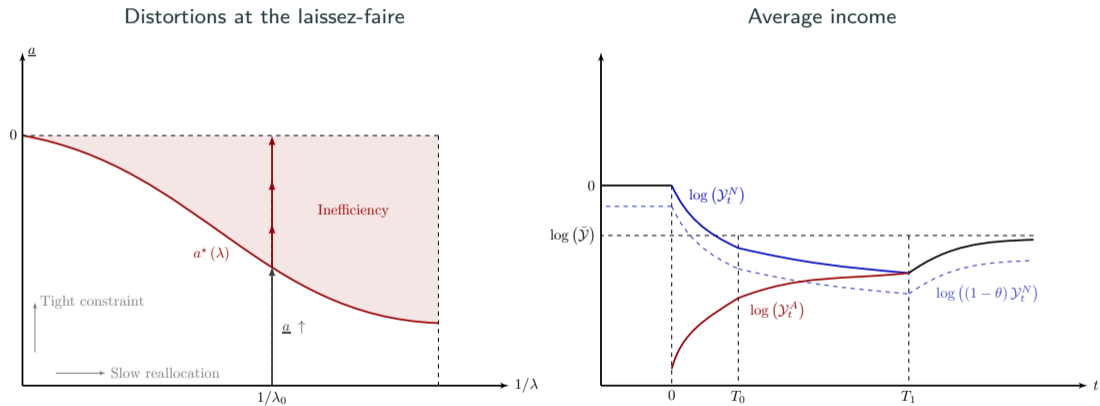
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Distortions at the laissez-faire



Efficient cases: instant realloc. (Costinot-Werning) or no borrowing frictions (Guerreiro et al)

Failure of the First Welfare Theorem



Workers expect income to improve as they reallocate \rightarrow Motive for **borrowing**

Why Is Automation Inefficient?

- Compare two optimality conditions for automation

(Firm at laissez-faire)

$$\int_0^{+\infty} e^{-\rho t} \underbrace{\frac{u'(c_{0,t}^N)}{u'(c_{0,0}^N)}}_{\exp(-\int_0^t r_s ds)} \Delta_t^* dt = 0$$

(Valuing like displaced workers would)

$$\int_0^{+\infty} e^{-\rho t} \frac{u'(c_{0,t}^A)}{u'(c_{0,0}^A)} \Delta_t^* dt = 0$$

where Δ_t^* is the IRF of Y to automation.

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- ▶ No borrowing constraints $\rightarrow \frac{u'(c_{0,t}^N)}{u'(c_{0,0}^N)} = \frac{u'(c_{0,t}^A)}{u'(c_{0,0}^A)} \rightarrow$ First best = Laissez-faire

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Firms fail to internalize that displaced workers have a limited ability to smooth consumption while they reallocate.

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When is $\tau^\alpha = 0$? **Redistributive tools** \rightarrow alleviate borrowing cons. and close MRS gap

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1. **Worker/time-specific lump sum transfers** → implement any **first best** (SWT holds)
Info requirements? Take-up? Political? (Piketty-Saez, 2013; Guerreiro et al., 2017; Costinot-Werning, 2018)

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2. **Symmetric lump sum transf.** (UBI) \rightarrow govt. borrows for workers \rightarrow restore **efficiency**
Fiscal cost? Distortions? Tighten constraints? (Guner et al., 2021, Aiyagari-Mcgrattan, 1998)

Constrained Ramsey problem

- ▶ **Second best tools:** tax automation (*ex ante*) + labor market interventions (*ex post*)

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- ▶ **Primal problem:** control automation α and reallocation T_0

$$\max_{\{\alpha, T_0, \mu_t, c_t\}} \sum_h \phi^h \eta^h \int_0^{+\infty} \exp(-\rho t) u(c_t^h) dt$$

subject to workers' budget constraints, the law of motion of labor, firms choosing labor optimally, and market clearing.

Constrained inefficiency (regardless of Pareto weights)

- ▶ Government's optimality conditions to **automate** (α) and **reallocate** (T_0)

$$\int_0^{+\infty} \exp(-\rho t) \frac{u'(c_{0,t}^N)}{u'(c_{0,0}^N)} \Delta_t^* dt = -\Phi^*(\alpha^{\text{SB}}, T_0^{\text{SB}}; \eta)$$
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Proposition. (Constrained inefficiency)

Fix weights η . Then, there is always a small perturbation of the technology $G^*(\cdot)$ such that either $\Phi^*(\cdot) \neq 0$ or $\Phi(\cdot) \neq 0$ — i.e., the equilibrium is *generically* constrained inefficient.

Taxing automation on efficiency grounds

- ▶ **No pref. for redistribution:** weights η^{effic} so that distributional terms cancel out
Government does not distort an efficient alloc. to improve redistribution

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(second best)

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→ Optimal to **tax automation** on efficiency grounds

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The optimal **tax on automation** improves **aggregate efficiency**. It raises consumption early on in the transition, precisely when displaced workers value it more.

Extension: Gradual automation

- ▶ Tax capital in the long-run → improve **insurance** or prevent **dynamic inefficiency**
(Aiyagari, 1995; Chamley, 2001; Conesa et al., 2009; Dávila et al., 2021; Aguiar et al.; 2021)

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Environment

Efficient Allocation

Decentralized Equilibrium

Failure of First Welfare Theorem

Optimal Policy

Quantitative Analysis

Firm

task-based framework – Acemoglu-Autor

$$y_t^h = F(\mu_t^h; \alpha_t^h) = A^h (\varphi^h \alpha_t^h + \mu_t^h)^{1-\eta}$$

quadratic adjustment costs – $\omega (x_t/\alpha_t)^2 \alpha_t$

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Workers

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uninsured risk – Huggett-Aiyagari

$$dz_t^T = -\rho_z z_t^T dt + \sigma_z dW_t$$

$$z_t^P = (1 - \theta) z_{t,-}^P \text{ when moving}$$

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Calibration

internal (7) and external (14)

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► Incomes and Government

► Parameters

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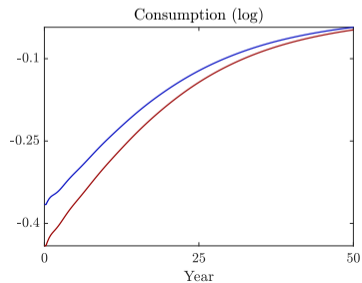
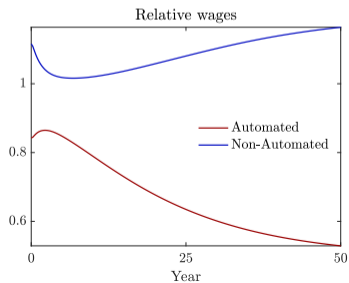
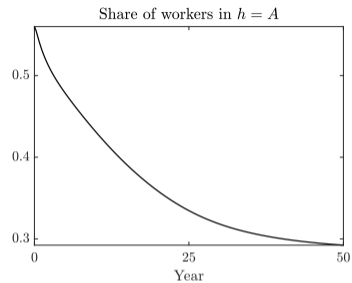
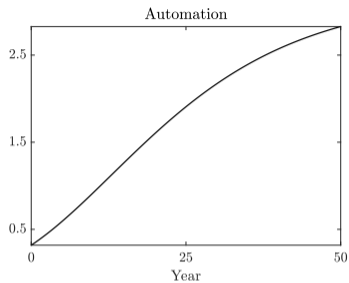
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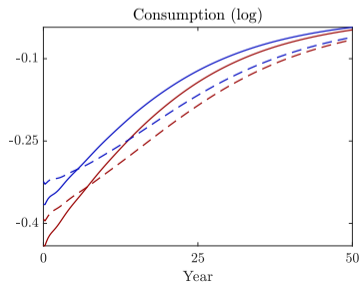
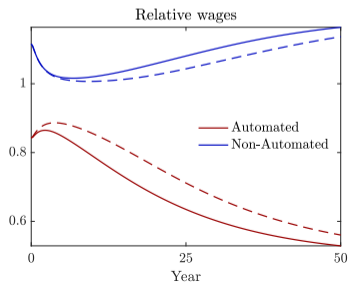
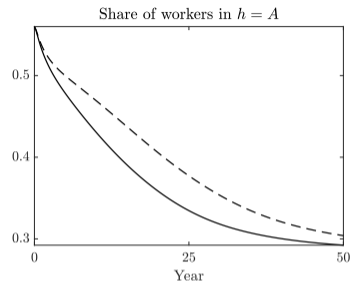
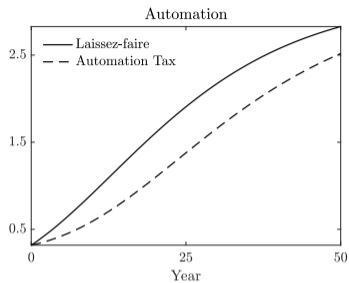
► Parameters

► Example

Automation, Reallocation and Inequality



Automation, Reallocation and Inequality



- ▶ **Objective:** The government maximizes

$$\mathcal{W}(\eta) \equiv \int_{-\infty}^{+\infty} \int \eta_t(\mathbf{x}) V_t^{\text{birth}}(\mathbf{x}) d\pi_t(\mathbf{x}) dt$$

- ▶ **Second best:** Choose $\{\tau_t^x\}$ on investment, rebated to firm owners.
- ▶ **Numerically:** Iterate on $\{\tau_t^x\}$ (parametrically) to find the second best.

Welfare Gains Form Slowing Down Automation

Table: Welfare Gains at Second Best Intervention

		Alternative calibrations		Alternative policies	
	Benchmark	Long unempl.	High liquid.	Transfers	Joint
Efficiency	3.8%				
Utilitarian	5.9%				

Note: 'Long unempl.' and 'High liquid.' are alternative calibrations with $1/\kappa = 2$ and $-B/Y = 1.4$. 'Transfers' denotes \$10k to automated workers. 'Joint' denotes optimal tax on automation and transfers.

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- ▶ Half-life of automation: 20 years at LF and 47 years at SB in our benchmark

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Takeaways

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 1. Automation is **inefficient** when frictions are sufficiently severe
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 2. Optimal to **slow down automation** while workers reallocate, but not tax it in the long-run
 - Improve aggregate efficiency by raising consumption when displaced workers are constrained

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 2. Optimal to **slow down automation** while workers reallocate, but not tax it in the long-run
 - Improve aggregate efficiency by raising consumption when displaced workers are constrained
- ▶ Quantitatively: substantial **efficiency** and **welfare gains** from slowing down autom.
 - Even when the government can implement generous transfers

Contributions to the Literature

Taxation of automation. Naito (1999), Guerreiro et al. (2017), Thuemmel (2018), Rebelo et al. (2018), Costinot-Werning (2020), Jaimovich et al. (2020); Acemoglu et al. (2020); Korinek-Stiglitz (2021)

- ★ Policy interventions on **efficiency grounds**

Labor reallocation. Lucas-Prescott (1974), Alvarez-Veracierto (1999, 2001), Alvarez-Shimer (2011); Keane-Wolpin (1997), Lee-Wolpin (2006); Davis-Haltiwanger (1999), Kambourov-Manovskii (2009)

- ★ Normative analysis with **incomplete markets**

Optimal policy in HA economies. Aiyagari (1995), Golosov-Tsyvinski (2006), Conesa-Krueger (2006), Conesa et al. (2009), Davila et al. (2012), Heathcote et al. (2017), Aguiar et al. (2021)

- ★ Focus on **taxation of automation** with **labor reallocation frictions**

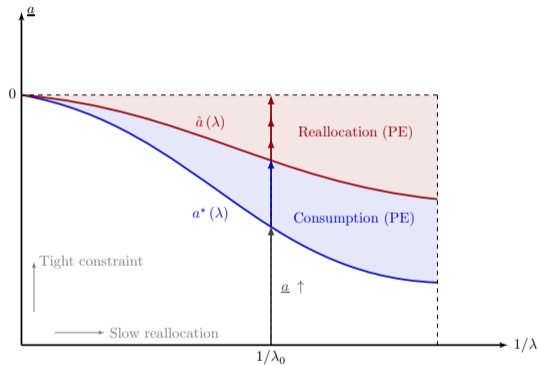
- ▶ **Example.** A task-based technology (Acemoglu-Restrepo, 2018):

$$\begin{aligned} G(\mu^A, \mu^N; \alpha) &= \exp \left(\int_0^\phi \log(\varphi\alpha + \mu^A) + \int_{1-\phi}^1 \log(\mu^N) \right) \\ &= (\varphi\alpha + \mu^A)^\phi (\mu^N)^{1-\phi} \end{aligned}$$

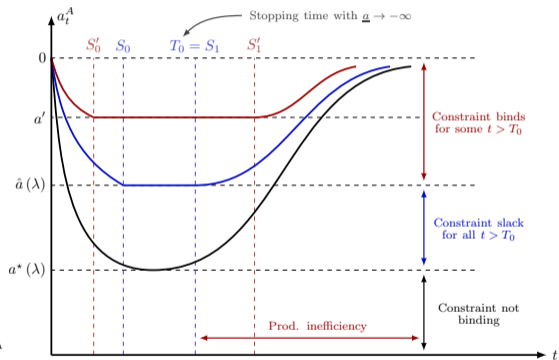
- ▶ Automation and labor are perfect substitutes *within* occupations.
- ▶ They can still be complements *across* occupations.
- ▶ **Quantitative model.** Specification above with gross complements across occup.

Borrowing

Distortions at the laissez-faire

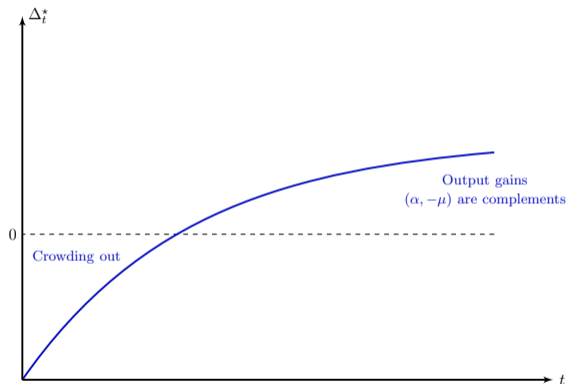


Distributional effects



Automation returns Δ_t^* are back-loaded

- **Assumption** (complementarity). $\partial_\alpha G^*(\mu, 1 - \mu; \alpha)$ has increasing differences in $(\alpha, -\mu)$



Extension I: No Labor Market Intervention

- ▶ Active labor market interventions might not be available (Heckman et al., Card et al.)

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$$\int_0^{+\infty} e^{-\rho t} \sum_h \phi^h \eta^h \frac{u'(c_{0,t}^h)}{u'(c_{0,0}^h)} (\Delta_t^* + T_0'(\alpha^{SB}) \Delta_t) dt = 0$$

so that

Short unempl/retraining spells ($1/\kappa$ low) \rightarrow **tax α more**

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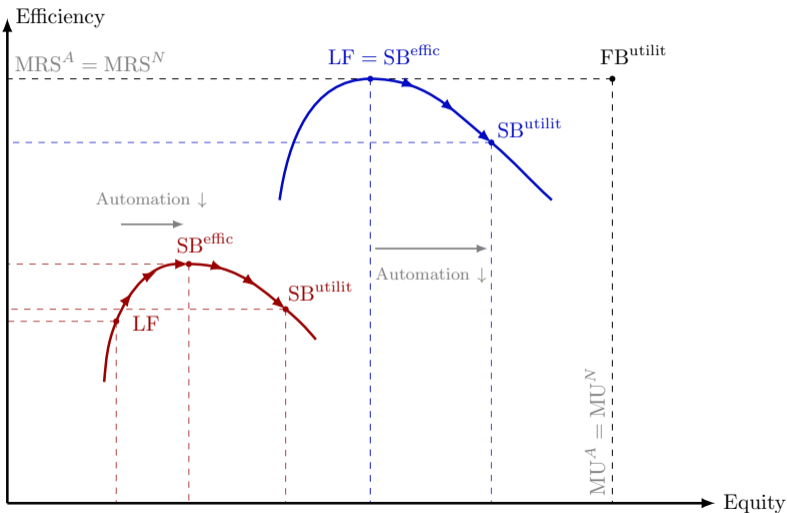
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- ▶ We play with the duration of these spells ($1/\kappa$) in our quantitative model.

Extension II: Equity concerns



Competitive Equilibrium

► **Incomes:**

$$\mathcal{Y}_t^*(\mathbf{x}) = \Pi_t + (1 - \tau_t) \times \begin{cases} \xi \exp(z) w_t^h & \text{if } e = E \\ b\xi \exp(z) w_t^{-h} & \text{if } e = U \end{cases}$$

where b is replacement rate during unemployment.

► **Assets:**

Workers trade riskless bonds, and annuities (Blanchard-Yaari)

► **Fiscal policy:**

Constant debt / GDP, adjusts distortionary tax $\{\tau_t\}$

► **Resource constraint:**

$$\int c_t(\mathbf{x}) d\pi_t + x_t + \omega \left(\frac{x_t}{\alpha_t} \right)^2 \alpha_t = G^* \left(\left\{ \frac{\int \mathbf{1}_{\{h(\mathbf{x})=h\}} \xi d\pi_t}{\phi^h} \right\} \right) + b \int \mathbf{1}_{\{e=U\}} \tilde{\mathcal{Y}}(\mathbf{x}) d\pi_t,$$

- **Parameters:** External calibration (14) and internal calibration (7)

Table 1: Internal Calibration

Parameter	Description	Calibration	Target / Source
ρ	Discount rate	0.10	2% real interest rate
A^A, A^N	Productivities	0.94, 1.16	Initial output (1)
ω	Adjustment cost	4	Routine empl. share 2015
ϕ	Fraction of automated occupations	0.55	Routine empl. share 1970
λ	Mobility hazard	0.312	Occupational mobility 1970
γ	Fréchet parameter	0.052	Elasticity of labor supply

Table 2: External Calibration

Parameter	Description	Calibration	Target / Source
σ	EIS (inverse)	2	-
χ	Death rate	1/50	Average working life of 50 years
$1 - \eta$	Initial labor share	0.64	1970 labor share (BLS)
δ	Depreciation rate	0.1	Graetz-Michaels (2018)
ν	Elasticity of substitution across occs.	0.75	Buera-Kaboski (2011)
$1/\kappa$	Average unemployment duration	1/3.2	Alvarez-Shimer (2011)
θ	Productivity loss from relocation	0.18	Kambourov-Manovskii (2009)
\underline{a}	Borrowing limit	0	Auclert et al (2018)
$\phi_0, \phi_1, -B/Y$	Government	0.35, 0.18, 0.26	Heathcote et al (2017), Kaplan et al (2018)
ρ_z, σ_z, b	Income	0.023, 0.102, 0.4	Floden-Lindé (2001), Shimer (2005)